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First results from two-dimensional bending angle operator for airborne radio occultations

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Develop a 2D forward operator for airborne radio occultations (ARO)

- 1. Based on ROPP 2D bending angle operator.
- 2. Minimum possible modifications to existing spaceborne operator.
- 3. Keep it simple and computationally-efficient.
- 4. To be used in JEDI software for data assimilation.

ARO obs data

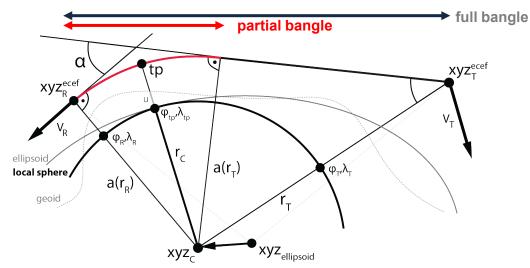
ARO data:

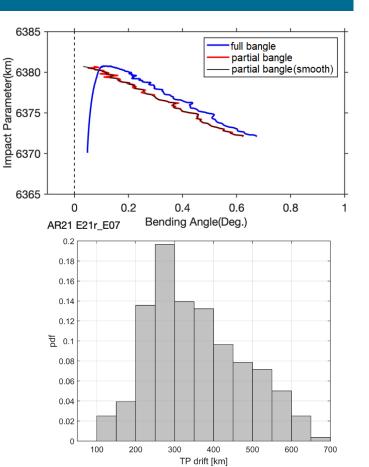
- geometrical optics (closed-loop receiver),
- positive and negative elevation angles,
- significant tangent point drift (particularly at uppermost levels at the aircraft).

Two variants of the bending angle:

partial: symmetrical section of the raypath around the occultation point below aircraft altitude

full: partial raypath section together with assymetrical section towards GNSS





ARO data formats

We follow UCAR/CDAAC data formats

Level1b atmPhs: atmospheric excess phase file with time as an independent variable

Level2 atmPrf: atmospheric profile

with vertical coordinate as an independent variable

Additional ARO-specific variables (function of time):

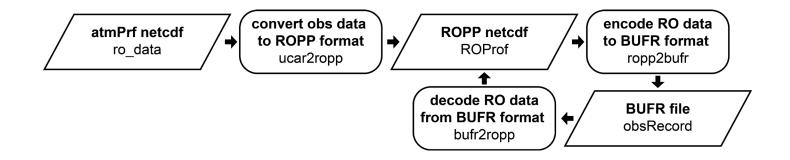
- in-situ refractivity at the aircraft
- aircraft height

ARO BUFR

In process...

Currently, ARO BUFR has the same structure and variables as spaceborne RO:

- · bending angles starts at the aircraft location
- both partial and full bending angles will be included
- refractivity structure as in spaceborne RO



Modifications to the 2D ray-tracer

Key features:

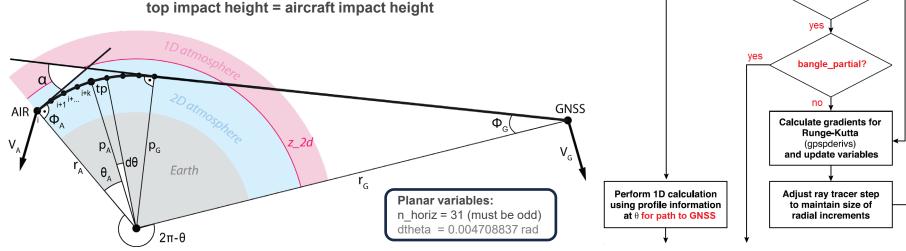
- integration starts at the obs tangent point outwards,
- · based on Runge-Kutta method,
- can account for **tangent point drift** (individual runs for each TP).

Variables:

z_2d: hard-coded, **upper limit for 2D ray-tracer**, currently set to 20 km (technically impact height / nr product)

y%r_air (new): radius of the aircraft to terminate integration on aircraft side.

Currently invariant during occultation due to BUFR limitations **top impact height = aircraft impact height**



Initialise step length,

r-rt=0 $\theta=0, \phi=\pi/2, \alpha_{12}=0$

Ray above z 2d?

Ray above y%r air?

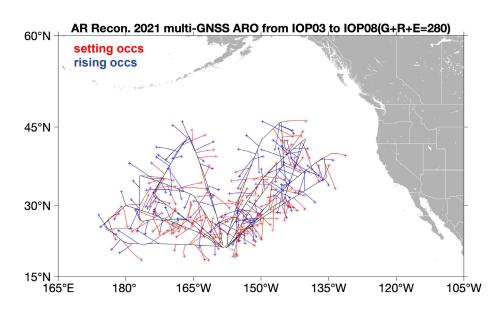
no

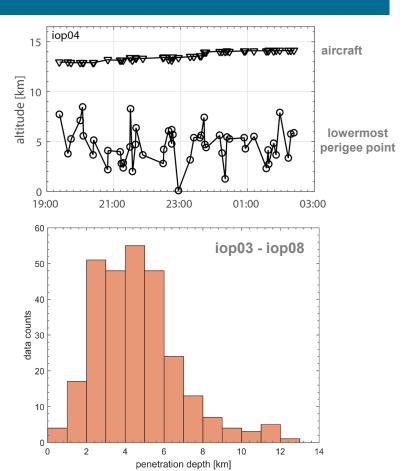
ves

ARO data from AR Recon 2021

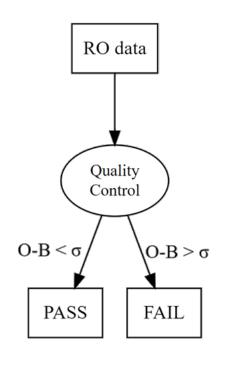
2021 Atmospheric River Reconnaissance (AR Recon) campaign:

- six intensive operating periods (IOPs)
- ARO data for 2021.022 2021.027
- 280 occultations in total (~40 per flight)





OmB statistics



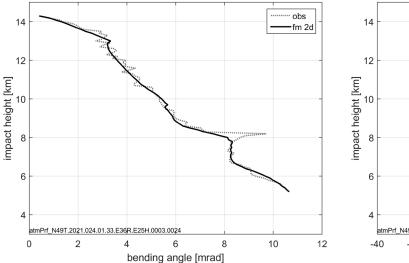
Obs errors based on OmB statistics for spaceborne RO:

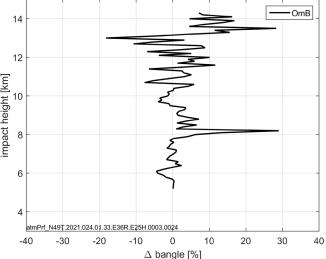
Bending angle: 10% at surface to 1% at 10 km

Refractivity: 1.1% at 4 km to 0.25% at 10 km

Sigma needs to be estimated for airborne RO

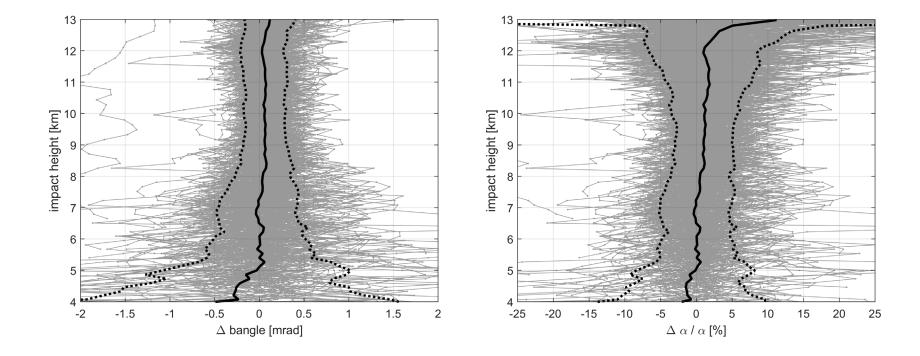
Typical threshold for rejection: **5** x sigma (standard deviation)





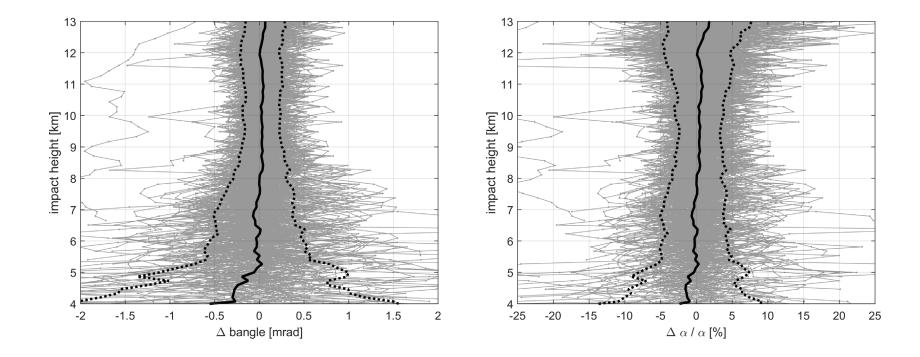
Overall statistics: iop03 – iop08 (280 occs)

Partial bending angle with tangent point drift



Overall statistics: iop03 – iop08 (280 occs)

Full bending angle with tangent point drift

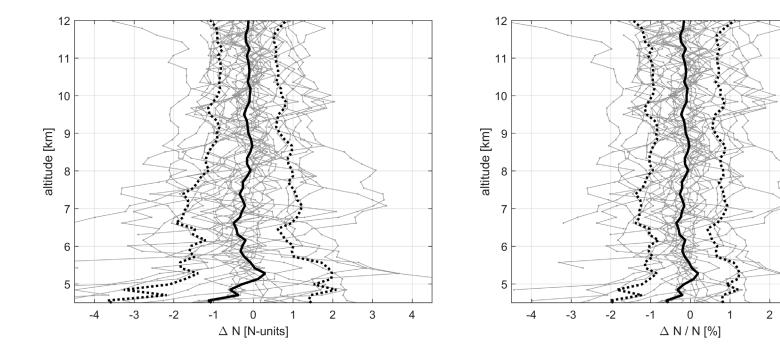


Overall statistics: iop03 – iop08 (37 occs)

Refractivity: ARO minus dropsonde collocation: +/- 1h, < 300 km

3

Δ



More N statistics: for 2021 (>750 occs)

1000

(a)

Mean SD

10

5

150

0.5%

ARO – ERA5

0

ALL

(870)

15 ·

MSL-Altitude (km) 01

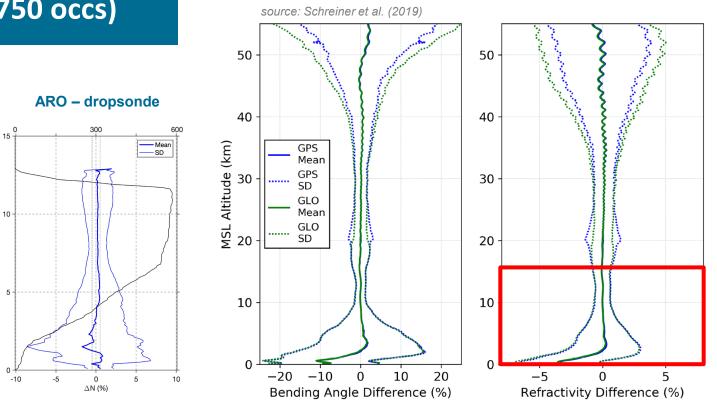
-10

-5

0

 ΔN (%)

COSMIC-2 for reference



Summary

- 1. ARO 2D bending angle operator:
 - can account for tangent point drift (significant for ARO),
 - ARO is good 1.5 km below flight level,
 - error properties in the midtroposphere comparable to spaceborne RO,
 - penetration depth limited by closed-loop data: down to approx. 4 km.
- 2. Future plans:
 - incorporate 2D ARO operator into JEDI (spaceborne operators already available),
 - ARO obs data: atmPrf and BUFR expected before the end of 2022 (endorsed by IROWG working group),
 - AR Recon 2022 raw data transmitted in real time, plans for AR Recon 2023 to develop NRT capability.

Thank you for your attention