

Monte Carlo methods,

in Physics: Theoretical Physics
Experimental Physics

Computational Physics: main tool is a Computer.

Large part of CP
is Monte Carlo
Computers, Moore's Law

Operates on models like Theo. P.
analyses "experiments" like Exp. P.

Principle of meas.
Apparatus
Calibration
Measurement

Algorithm
Program
Debugging
Run

Example: Ising model in the Canonical Ensemble

$S_{\vec{n}} \in \{1, -1\}$ spins

$\vec{n} \in \Omega$ d dimensional lattice

configurations:

+ + + - +
+ - - - +
- - + + -
+ - + - +
- + - - +

e.g.
 $\hat{v} = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$ unit
vector
in dir. \hat{v}

$|\Omega| = L^d = V$ number of lattice points

2^V configurations

$$H[S] = -J \sum_{\vec{n}} \sum_{\nu=1}^d S_{\vec{n}} \cdot S_{\vec{n}+\hat{\nu}} - \mu h \cdot \sum_{\vec{n}} S_{\vec{n}}$$

Hamilton function

Observable: e.g. Magnetisation $M[S] = \frac{1}{V} \cdot \sum_{\vec{n}} S_{\vec{n}}$

Canonical Ensemble

System coupled to heat reservoir with Temperature T

Thermal equilibrium

Probability of a conf. $P[S] = \frac{1}{Z} e^{-\beta H[S]}$

$$\beta = \frac{1}{k_B T}$$

$$Z = \sum_{\{S\}} e^{-\beta H[S]}$$

← sum over all 2^V configs.

$$k_B = 1.38 \cdot 10^{-23} \text{ J/K}$$

Boltzmann constant

Expectation value for observable $F[s]$

$$\langle F \rangle = \sum_{\{s\}} F[s] P[s] = \frac{1}{Z} \sum_{\{s\}} F[s] e^{-\beta H[s]}$$

Sum \uparrow e.g. $L=100$ $d=3$ $V=10^6$
of configs: $2^{10^6} = (2^{10})^{10^5} \approx (1000)^{10^5} = 10^{3 \cdot 10^5}$

No hope to calculate exactly numerically.

Fundamental theories

Quantum field theory (e.g. QCD 6 quarks & gluons)
Nuclear physics

A ϕ^4 Theory: Scalar field $\phi(x) \in \mathbb{R}$ $x = (\vec{x}, t)$

Defined by action

$$S(\phi(x)) = \int d^4x \mathcal{L}(\phi(x)) = \int d^4x \left[-\frac{1}{2} (\partial_\mu \phi(x)) (\partial^\mu \phi(x)) + \frac{m^2}{2} \phi^2(x) + \frac{g}{24} \phi^4(x) \right]$$

Quantum mechanical expectation value

can be calculated by Feynmann Path. Integral

self interaction \uparrow

$$\langle F \rangle = \frac{1}{Z} \int \mathcal{D}\phi e^{-\hbar^{-1} S[\phi]} \cdot F[\phi] \quad Z = \int \mathcal{D}\phi e^{-S[\phi]/\hbar}$$

$\mathcal{D}\phi$: Path integral: integration over field configs.

Can be defined on a lattice in a rigorous way.

$\phi(x) \rightarrow \phi(\vec{n})$ $\vec{n} \in \Omega$ 4d lattice

$\partial_\mu \phi(x) \rightarrow \frac{1}{2a} [\phi(\vec{n}+\hat{\mu}) - \phi(\vec{n}-\hat{\mu})]$ $a =$ lattice spacing

$$S[\phi] = \sum_{n \in \Omega} \left[-\frac{1}{2} \left(\frac{\phi(\vec{n}+\hat{\mu}) - \phi(\vec{n}-\hat{\mu})}{2a} \right)^2 + \frac{1}{2} m^2 \phi^2(\vec{n}) + \frac{g}{24} \phi^4(\vec{n}) \right]$$

$$\mathcal{D}\phi \rightarrow \prod_{n \in \Omega} d\phi(\vec{n})$$

$$\langle F \rangle = \frac{1}{Z} \int \prod_{n \in \Omega} d\phi(\vec{n}) e^{-S[\phi]/\hbar} F[\phi]$$

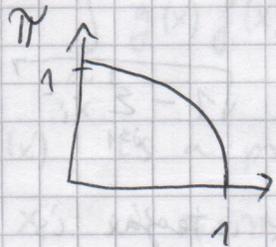
\leftarrow high dim. integral

Many areas:

Stat. Phys. (Particle Phys., Condensed matter, ...)
 Engineering, Climate change, weather predict.
 Finance, Statistical tests (eg. bootstrap)
 Biology
 Computer graphics, optimization,
 etc.

Monte Carlo Integration

"measuring" π

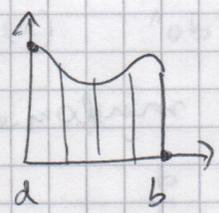


$$\int_0^1 \sqrt{1-x^2} dx = \frac{\pi}{4} = \int_0^1 dx \int_0^1 dy \Theta(1-x^2-y^2)$$

$$\Theta(x) = 0 \quad x < 0$$

$$\Theta(x) = 1 \quad x \geq 0$$

Method 1



Trapezoid Rule:

$$\int_a^b f(x) dx \approx \sum_{i=0}^{N-1} \left[f\left(a + i \frac{b-a}{N}\right) + f\left(a + (i+1) \frac{b-a}{N}\right) \right] \frac{N}{2(b-a)}$$

Method 2

Take random numbers with uniform distribution

$$r_i \in [0, 1] \quad i = 1 \dots 2N$$

$$x_i = r_i \quad y_i = r_{i+N}$$

$n_{in} = \#$ of indices for which $\sqrt{x_i^2 + y_i^2} < 1$

$$\frac{\pi}{4} \approx \frac{n_{in}}{N}$$

results eg:

N	π
100	3,244
1000	3,141
10000	3,1402
100000	3,1409

Results get better with more points

Can we say more?

each point has $p = \frac{\pi}{4}$ chance to be inside $q = 1 - \frac{\pi}{4}$ to be out

n_{in} has a binomial distribution $\langle \Delta n_{in}^2 \rangle = N \cdot p \cdot q$

$$\left\langle \Delta \left(\frac{n_{in}}{N} \right)^2 \right\rangle = \frac{1}{N} \cdot p \cdot q$$

Variance

Error: $\sqrt{\text{variance}} \sim \frac{1}{\sqrt{N}}$ 4 times the data
1/2 the error

Trapezoid rule Error $\sim \frac{1}{N^2}$ much better

Look at 10-sphere,

$$V \approx \frac{\pi^5}{120}$$

Measure/Calculate π from this

Method 1: Trapezoid rule: $\int_0^1 \pi dx_i \sqrt{1 - \sum_{i=1}^9 x_i^2}$

Error is still $\sim \frac{1}{N^2}$ if each integral is split to N

Method 2: Monte Carlo $x_i \in [0, 1]$ random

$$n_{in} = \# \text{ of } i \text{ with } \sum x_i^2 < 1$$

Take e.g. Trapezoid with $N = 100 = 10^2$

10^9 evaluations are needed.

Takes $O(1)$ seconds on a generic comp.

Monte Carlo with $N = 10^9$

$$\text{Error}_{\text{Trapezoid}} \sim \frac{1}{100}$$

$$\text{Error}_{\text{MC}} \sim \frac{1}{\sqrt{10^9}} = \frac{1}{10^{4.5}}$$

Monte Carlo much better

For high dim integrals, Trapezoid is quickly intractable

$$\text{Error} \sim \frac{1}{N^2} \quad M = N^d \text{ evaluations} \quad \text{Error} \sim \frac{1}{M^{2/d}}$$

Monte Carlo error independent of dim

$$\text{Error} \sim \frac{1}{\sqrt{M}} \quad \text{for } M \text{ evaluations}$$

Sampling



We calculated a 2d integral $\int_0^1 \int_0^{\sqrt{1-x^2}} \Theta(1-x^2-y^2)$

Can also do 1d integral $\int_0^1 \sqrt{1-x^2} dx = \lim_{N \rightarrow \infty} \frac{1}{N} \sum_{i=1}^N \sqrt{1-x_i^2}$

Generally $\int_a^b g(x) f(x) dx$

$x_i \in [0, 1]$ uniform.

$f(x)$ is a probability dist. $f(x) \geq 0$ $\int f(x) = 1$

x is a random variable (can be a vector in many d)

$g(x)$ "observable"

Take x_i $i=1 \dots N$ random

$$\int_a^b g(x) f(x) dx \approx \frac{1}{N} \sum_{i=1}^N g(x_i) = g_{\text{Est}} \quad \text{MC estimator.}$$

Variance assuming independent x_i

$$\sigma_{g_{\text{Est}}}^2 = \frac{1}{N^2} \sum_{i=1}^N \sigma_{g(x_i)}^2 = \frac{\sigma_g^2}{N} \Rightarrow \text{Error} \sim \frac{1}{\sqrt{N}}$$

We have some freedom; e.g. but $f(x) \geq 0$, $\int f(x) = 1$

$$\int_0^1 \sqrt{1-x^2} dx = \int_0^1 \sqrt{(1+x)(1-x)} dx = \int_0^1 \frac{1}{2} \sqrt{\frac{1+x}{1-x}} \cdot 2(1-x) dx$$

$$g(x) = \sqrt{1-x^2} \quad \text{or} \quad g(x) = 1$$

$$f(x) = 1 \quad \text{or} \quad f(x) = \sqrt{1-x^2}$$

$$g(x) = \frac{1}{2} \sqrt{\frac{1+x}{1-x}} \quad f(x) = 2(1-x)$$

$f(x) = 1$ simple sampling

$f(x) \neq 1$ biased sampling, importance sampling

in physics usually $f(x) = \text{Boltzmann factor} = e^{-\beta H}$