

V.A. Kovtunenکو

Quasistatic Propagation of Cracks¹

The problem of shape perturbation for the variational inequality describing solids with cracks under the nonpenetration condition is considered [1, 4]. The obtained asymptotic results are applied to describe the quasistatic propagation of cracks [2, 3, 7].

1. Perturbation of the crack problem. Let Ω be a bounded domain in \mathbf{R}^N , $N = 2, 3$, with the boundary, which includes two parts $\Gamma_{\mathcal{D}}$ and $\Gamma_{\mathcal{N}}$, $\Gamma_{\mathcal{D}} \cap \Gamma_{\mathcal{N}} = \emptyset$. Consider the crack $\Gamma(0)$ inside Ω as the $(N - 1)$ -manifold in \mathbf{R}^N . We denote the domain with crack as $\Omega(0) = \Omega \setminus \overline{\Gamma(0)}$. For small enough parameter ε , we consider the function of perturbation $\Phi \in [C^2(-\varepsilon_0, \varepsilon_0; W^{1,\infty}(\mathbf{R}^N))]^N$ with $\Phi(0)(x) = x$, $x \in \mathbf{R}^N$. Let $\Phi(\varepsilon)(\Omega) = \Omega$, then the coordinate transformation $y = \Phi(\varepsilon)(x)$ transforms the initial domain $\Omega(0)$ to the perturbed domain $\Omega(\varepsilon) = \Omega \setminus \overline{\Gamma(\varepsilon)}$ with $\Gamma(\varepsilon) = \Phi(\varepsilon)(\Gamma(0))$. We assume that for each ε the domain Ω can be splitted into two subdomains with Lipschitz-continuous boundaries and common interface, which intersects $\Gamma_{\mathcal{D}}$, such that $\Gamma(\varepsilon)$ is a part of this interface.

The Jacobian of transformation has the asymptotic $J(\varepsilon) = 1 + \varepsilon \operatorname{div}(V) + o(\varepsilon)$, where $V \in [W^{1,\infty}(\mathbf{R}^N)]^N$ denotes the velocity field $\frac{\partial \Phi}{\partial \varepsilon}|_{\varepsilon=0}$. Therefore, $\Phi(\varepsilon)$ yields the one-to-one correspondence between domains $\Omega(0)$ and $\Omega(\varepsilon)$, also between spaces $\widetilde{H}^1(\Omega(0))$ and $\widetilde{H}^1(\Omega(\varepsilon))$, when we introduce the space

$$\widetilde{H}^1(\Omega(\varepsilon)) = \{u \in [H^1(\Omega(\varepsilon))]^N, \quad u = 0 \quad \text{on } \Gamma_{\mathcal{D}}\}.$$

For the displacement vector $u = (u_1, \dots, u_N)$ we consider the linear elasticity model of nonhomogeneous anisotropic solid

$$\sigma_{ij}(u) = c_{ijkl} \epsilon_{kl}(u), \quad \epsilon_{ij}(u) = 0.5(u_{i,j} + u_{j,i}), \quad i, j = 1, \dots, N,$$

with elasticity coefficients $c_{ijkl} \in C^2(\mathbf{R}^N)$, $i, j, k, l = 1, \dots, N$, which are symmetric and elliptic as it is usually supposed. Let us choose the unit normal

¹The research results were obtained with support of the INTAS Foundation in framework of the research grant YSF 01/1-33, and visiting Professor W.L. Wendland at the Mathematical Institute A of the University of Stuttgart. The participation in the International Conference on Multifield Problems on 8-10 April, 2002, in Stuttgart was supported by the German Research Foundation (DFG) in framework of the Collaborative Research Programme (SFB) 404.

vector $\nu(\varepsilon)$ to $\Gamma(\varepsilon)$ to distinguish its two opposite faces $\Gamma^\pm(\varepsilon)$, which correspond to $\pm\nu(\varepsilon)$, respectively. Then we introduce the closed convex set of admissible displacements

$$K(\varepsilon) = \{u \in \widetilde{H}^1(\Omega(\varepsilon)), \quad \llbracket u \rrbracket \nu(\varepsilon) \geq 0 \quad \text{on } \Gamma(\varepsilon)\}, \quad \llbracket u \rrbracket = u|_{\Gamma^+(\varepsilon)} - u|_{\Gamma^-(\varepsilon)},$$

which yields the condition of mutual nonpenetration between the crack faces. For the given traction force $g = (g_1, \dots, g_N) \in [L^2(\Gamma_N)]^N$, there exists the unique solution $u(\varepsilon) \in K(\varepsilon)$ of the variational inequality

$$\int_{\Omega(\varepsilon)} \sigma_{ij}(u(\varepsilon)) \epsilon_{ij}(v - u(\varepsilon)) \geq \int_{\Gamma_N} g_i(v - u(\varepsilon))_i \quad \forall v \in K(\varepsilon) \quad (1)$$

describing static equilibrium of the solid with crack.

2. Asymptotics of the solution and energy. When $\nu(\varepsilon) \circ \Phi(\varepsilon) = \nu(0)$, then $\Phi(\varepsilon)$ provides the one-to-one correspondence between $K(0)$ and $K(\varepsilon)$, too. In this case, the transformed solution of (1) as the function $u(\varepsilon) \circ \Phi(\varepsilon) \in K(0)$ solves the following variational inequality

$$\begin{aligned} & \int_{\Omega(0)} J(\varepsilon)(c_{ijkl} \circ \Phi(\varepsilon)) E_{kl}(\Psi(\varepsilon); u(\varepsilon) \circ \Phi(\varepsilon)) E_{ij}(\Psi(\varepsilon); v - u(\varepsilon) \circ \Phi(\varepsilon)) \\ & \geq \int_{\Gamma_N} g_i(v - u(\varepsilon) \circ \Phi(\varepsilon))_i \quad \forall v \in K(0), \end{aligned} \quad (2)$$

where $E_{ij}(\Psi; u) = 0.5(u_{i,k} \Psi_{kj} + u_{j,k} \Psi_{ki})$, $\Psi = (\frac{\partial \Phi}{\partial x})^{-1}$, $i, j = 1, \dots, N$. From (2) and (1) as $\varepsilon \rightarrow 0$ we prove the estimates

$$\|u(\varepsilon) \circ \Phi(\varepsilon)\|_{\widetilde{H}^1(\Omega(0))} \leq c_0, \quad \|u(\varepsilon) \circ \Phi(\varepsilon) - u(0)\|_{\widetilde{H}^1(\Omega(0))} \leq c_1 \varepsilon. \quad (3)$$

This provides existence of the weak material derivative $\dot{u}(\Phi) \in Z(u(0))$ in the sense

$$\varepsilon_n^{-1}(u(\varepsilon_n) \circ \Phi(\varepsilon_n) - u(0)) \rightarrow \dot{u}(\Phi) \quad \text{weakly in } \widetilde{H}^1(\Omega(0)) \quad \text{as } \varepsilon_n \rightarrow 0. \quad (4)$$

Here $Z(u(0))$ is a tangential hyperplane to $K(0)$ at $u(0)$, i.e. $Z(u(0)) = \{u \in \widetilde{H}^1(\Omega(0)), \llbracket u \rrbracket \nu(0) \geq 0 \quad \text{on } C(u(0)), \int_{\Omega(0)} \sigma_{ij}(u(0)) \epsilon_{ij}(u) = \int_{\Gamma_N} g_i u_i\}$, for $C(u(0)) \subseteq \Gamma(0)$ being the coincidence set where $\llbracket u(0) \rrbracket \nu(0) = 0$. Moreover, with the help of (3) and (4) we prove two orthogonality conditions

$$\int_{\Omega(0)} \sigma_{ij}(u(0)) \epsilon_{ij}(\dot{u}(\Phi)) = \int_{\Gamma_N} g_i \dot{u}(\Phi)_i = - \int_{\Omega(0)} A_1(V; u(0), u(0)) \quad (5)$$

with the symmetric bilinear form as follows:

$$A_1(V; u, v) = \text{div}(V c_{ijkl}) \epsilon_{kl}(u) \epsilon_{ij}(v) - \sigma_{ij}(u) E_{ij}(\frac{\partial V}{\partial x}; v) - \sigma_{ij}(v) E_{ij}(\frac{\partial V}{\partial x}; u).$$

Let us introduce the function of potential energy $P(\Phi) : (-\varepsilon_0, \varepsilon_0) \rightarrow \mathbf{R}$ by the relation

$$P(\Phi)(\varepsilon) = 0.5 \int_{\Omega(\varepsilon)} \sigma_{ij}(u(\varepsilon)) \epsilon_{ij}(u(\varepsilon)) - \int_{\Gamma_{\mathcal{N}}} g_i u(\varepsilon)_i. \quad (6)$$

Applying the coordinate transformation $y = \Phi(\varepsilon)(x)$ to the integrals in (6), due to (3)–(5) the following expansion holds

$$P(\Phi)(\varepsilon) = P(\Phi)(0) + \varepsilon P'(\Phi)(0) + o(\varepsilon),$$

with the first derivative of potential energy as follows:

$$P'(\Phi)(0) = 0.5 \int_{\Omega(0)} A_1(V; u(0), u(0)). \quad (7)$$

It is independent on the choice of perturbation function Φ in the sense that, if $\Omega(\varepsilon) = \Phi^1(\varepsilon)(\Omega(0)) = \Phi^2(\varepsilon)(\Omega(0))$, then $P'(\Phi^1)(0) = P'(\Phi^2)(0)$. Similar to (7) formula for constant elasticity coefficients and V of the $W^{2,\infty}$ -class was firstly obtained in [5], and for the partial case of perturbation in [6]. When there exists $D \subset \Omega(0)$ such that $u(0) \in H^2(\overline{D})$, $V = 0$ or $\{\nabla c_{ijkl}\} = 0$ in $\overline{\Omega}(0) \setminus D$, and $c_{ijkl}(x) \xi_{kl} [0.5 \operatorname{div}(V(x)) \xi_{ij} - \xi_{im} V_{m,j}(x)] = 0$ for all $\{\xi_{ij}\}$ a.e. $x \in \Omega(0) \setminus \overline{D}$, then, integrating by parts, the domain integral in (7) can be represented in the equivalent form of integral over boundary ∂D ,

$$I(V) = \int_{\partial D} \sigma_{ij}(u(0)) [0.5(V \cdot n) \epsilon_{ij}(u(0)) - n_j (V \cdot \nabla u(0)_i)],$$

where n is the unit outward normal vector to ∂D . This implies the general form of invariant integrals of energy.

3. Numerical example on the crack propagation. Let $\Omega \in \mathbf{R}^2$ be the unit square $\{0 < x_1 < 1, |x_2| < 0.5\}$ with the boundary $\overline{\Gamma}_{\mathcal{N}} \cup \overline{\Gamma}_{\mathcal{D}}$, $\Gamma_{\mathcal{D}} = \{x_1 = 1, |x_2| < 0.5\}$. Let us take the crack $\Gamma(0) = \{0 < x_1 < l, x_2 = 0\}$ of the length $0 < l < 1$. In this case $\nu(0) = (0, 1)$. The Lamé model $\sigma_{ij}(u) = 2\mu \epsilon_{ij}(u) + \lambda(\epsilon_{11}(u) + \epsilon_{22}(u)) \delta_{ij}$, $i, j = 1, 2$, with $\mu = \frac{E}{2(1+\nu)}$, $\lambda = \frac{E\nu}{(1+\nu)(1-2\nu)}$, $\nu = 0.34$, $E = 7.3 \cdot 10^4 (mPa)$ is considered. We take the traction force g given on $\Gamma_{\mathcal{N}} = \Gamma_{\mathcal{N}}^1 \cup \Gamma_{\mathcal{N}}^2$ by the following functions

$$\begin{cases} g_1(x) = -6.5t_0\mu|2x_2|, & g_2(x) = 0 & \text{on } \Gamma_{\mathcal{N}}^1 = \{x_1 = 0, 0 < \pm x_2 < 0.5\} \\ g_1(x) = 0, & g_2(x) = \pm t_0\mu(1 - |2x_1 - 1|) & \text{on } \Gamma_{\mathcal{N}}^2 = \{0 < x_1 < 1, x_2 = \pm 0.5\} \end{cases}$$

with the multiplier $t_0 = 0.9 \cdot 10^{-3}$.

The inequality (1) as $\varepsilon = 0$ is approximated by the penalty equation

$$\int_{\Omega(0)} \sigma_{ij}(u^\delta(0)) \epsilon_{ij}(v) - \frac{1}{\delta} \int_{\Gamma(0)} \llbracket u_2^\delta(0) \rrbracket^- \llbracket v_2 \rrbracket = \int_{\Gamma_N} g_i v_i, \quad u^- = \max\{0, -u\},$$

with small parameter $\delta > 0$, and then linearized by iterations as follows:

$$\begin{aligned} & \int_{\Omega(0)} \sigma_{ij}(u^{\delta,n}(0)) \epsilon_{ij}(v) + \frac{1}{\delta} \int_{\Gamma(0)} \llbracket u_2^{\delta,n}(0) - u_2^{\delta,n-1}(0) \rrbracket \llbracket v_2 \rrbracket \\ & = \int_{\Gamma_N} g_i v_i + \frac{1}{\delta} \int_{\Gamma(0)} \llbracket u_2^{\delta,n-1}(0) \rrbracket^- \llbracket v_2 \rrbracket, \quad n = 1, 2, \dots \end{aligned} \quad (8)$$

We have the convergences

$$\|u^\delta(0) - u(0)\|_{\tilde{H}^1(\Omega(0))} \rightarrow 0 \quad \text{as } \delta \rightarrow 0 \quad (\text{of the order } \sqrt{\delta}),$$

$$\|u^{\delta,n}(0) - u^\delta(0)\|_{\tilde{H}^1(\Omega(0))} \leq (1 + C\delta)^{-0.5n} \|u^{\delta,0}(0) - u^\delta(0)\|_{\tilde{H}^1(\Omega(0))}.$$

To solve numerically the linear equation (8), we apply the finite-element method with piecewise-linear functions on uniform triangle mesh in $\Omega(0)$ of the size $h = 0.025$. It supposed the approximation of order \sqrt{h} for $u(0)$ and order h for the energy. Approximate values of the potential energy $P(\Phi)(0)$ from (6), calculated by this scheme, are shown in Fig.1 in dependence on the parameter l of the crack length.

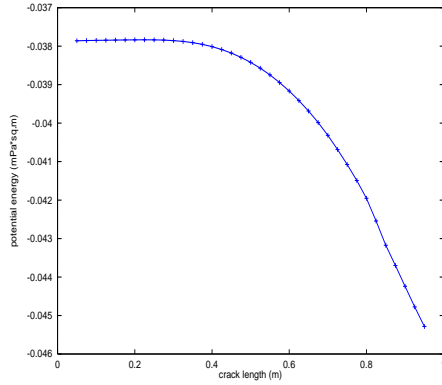


Fig.1. Potential energy $P(\Phi)(0)$

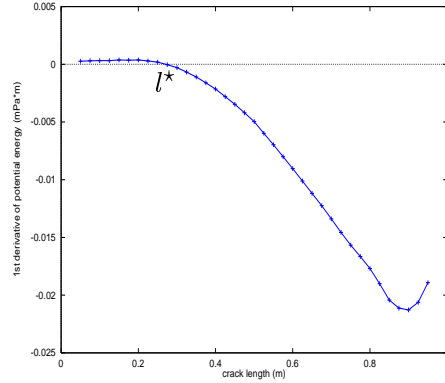


Fig.2. First derivative $P'(\Phi)(0)$

Let us take the piecewise-linear cut-off function $\chi \in W^{1,\infty}(\mathbf{R}^2)$, which has $\text{supp}(\chi) \subset \Omega$ and $\chi = 1$ in neighborhood of the crack tip $x = (l, 0)$. Applying the perturbation $\Phi(\varepsilon)(x) = (x_1 + \varepsilon\chi(x), x_2)$, it follows from formula (7) the

first derivative $P'(\Phi)(0)$ with respect to perturbation of the crack length l (energy release rate), which is numerically calculated as shown in Fig.2. Here $P'(\Phi)(0) \approx 0$ for $0 < l \leq l^*$, $l^* \approx 0.25$. Moreover, from the well-known formula in classical fracture mechanics, $-P'(\Phi)(0) = 0.5\mu(1 - \nu)|K|^2$, due to $P'(\Phi)(0) \leq 0$ we can find the modulus $|K|$ of stress intensity factors as shown in Fig.3.

For loading parameter $t \geq 0$, let us consider the linear loading $g(x)(t) = tg(x)$. By the cone property of $K(0)$ we obtain that $u(0)(t) = tu(0) \in K(0)$ is a solution of the corresponding quasistatic problem, and, therefore, $P'(\Phi)(0)(t) = t^2P'(\Phi)(0)$. Let us fix the initial crack length l . From the Griffith fracture criterion $\gamma + P'(\Phi)(0)(t) = 0$, we deduce then the critical value of the maximal loading as

$$g_{\text{cr}}(l) = 6.5t_0\mu t_{\text{cr}}(l), \quad t_{\text{cr}}(l) = \sqrt{\gamma(-P'(\Phi)(0))^{-1}},$$

and the inverse relation $l = l(g_{\text{cr}})$ shown in Fig.4 as the curve L . Here constant $\gamma > 0$ is the doubled density of surface energy distributed at the crack. The Griffith fracture hypothesis implies that there is no crack growth for $0 \leq t < t_{\text{cr}}(l)$, and the crack starts to grow when $t = t_{\text{cr}}(l)$. In Fig.4 we see three possible cases of the crack quasistatic propagation in dependence on the initial crack length l . The crack does not grow at all for $l \leq l^*$ with l^* from Fig.2. For $l > l^*$ the crack propagation can be stable (with finite initial velocity), as shown in Fig.4 for $l = 0.95$, or unstable with a jump (infinite initial velocity), as shown in Fig.4 for $l = 0.825$.

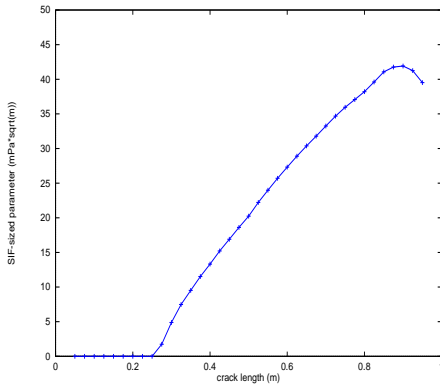


Fig.3. Modulus of SIF $|K|$

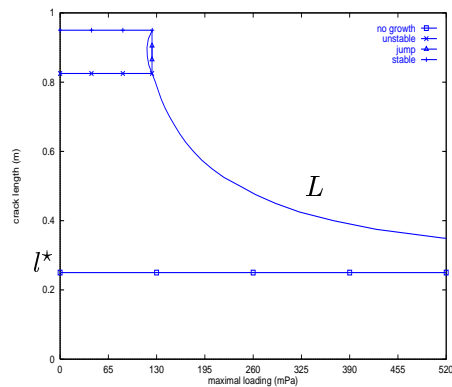


Fig.4. Critical loading $g_{\text{cr}}(l)$

REFERENCES

- [1] Bach M., Khludnev A.M., Kovtunenکو V.A., Derivatives of the energy functional for 2D-problems with a crack under Signorini and friction conditions, *Math. Meth. Appl. Sci.* **23** (2000), 6, 515–534.
- [2] Bach M., Kovtunenکو V.A., Numerics of quasistatic crack propagation and delamination of interface cracks. I&II, *SFB404 Bericht 2001/16&17*, Universität Stuttgart 2001.
- [3] Bach M., Kovtunenکو V.A., Sukhorukov I.V., Numerical validation of the shape optimization approach to quasi-static crack propagation, *SFB404 Bericht 2000/29*, Universität Stuttgart 2000.
- [4] Khludnev A.M., Kovtunenکو V.A., *Analysis of Cracks in Solids*, WIT-Press, Southampton, Boston 2000.
- [5] Khludnev A.M., Ohtsuka K., Sokolowski J., On derivative of energy functional for elastic bodies with cracks and unilateral conditions, *Les prepublications dé Institut Elie Cartan* **20** (2000).
- [6] Khludnev A.M., Sokolowski J., The Griffith formula and the Cherepanov-Rice integral for crack problems with unilateral conditions in non-smooth domains, *Euro. J. Appl. Math.* **10** (1999), 379–394.
- [7] Kovtunenکو V.A., Sensitivity of cracks in 2D-Lamé problem via material derivatives, *J. Appl. Math. Phys. (ZAMP)* **52** (2001), 6, 1071–1087.

*address: V.A. Kovtunenکو, Lavrent'ev Institute of Hydrodynamics,
630090 Novosibirsk, Russia; e-mail: kovtunenکو@hydro.nsc.ru*